

IMS51 Series Driver

5 Phase Stepper Driver Units

- A compact package matching most existing motors
- 100~120Vac or 200~220Vac Single Phase Power Input
- Opto-isolated inputs and outputs
- Auto-current down feature
- Half Step/Full Step setting selection



1. Specifications

Model	IMS51-110	IMS51-210	IMS51-120	IMS51-220
Power Requirement	AC100-120V±	10% 50/60Hz	AC200-220V±	10% 50/60Hz
Power Consumption	400 VA max	650 VA max	500 VA max	850VA max
Drive Methods		Star Bi-polar ; constant	current chopper driver	
Output Current	1.4 Amp per phase	2.8 Amp per phase	1.4 Amp per phase	2.8 Amp per phase
Resolution	Basic Step : 0.72° (1:Full Step , ½:Half	Step)		
Function	Auto-current down at outputs	standstill, Auto-current (OFF, MONITOR and O	VERHEAT indicator
Input Signals		CW/CCW) , CO Input resistance : 390 Ω Voltage H : 4~5V L :		
CW / CCW (preferred pulse type)	In Bi-Clock mode Clockwise direction pulses applied to the CW input. Counter clockwise direction pulses applied to the CCW input. Rising edge of input pulse starts to move. Timing chart of Bi-Clock signal			
Pulse / Direction	In Pulse / Direction model Stepping pulses application logic signal and Rising edge of input some signal and the second signal and the second signal and the second signal and second signal signal signal and second signal	ed to the Pulse input. applied to the CW/CCW tarts to move.	/ input.	
Output Signal	MONITOR, HEAT SIG	GNAL output. All Opto Is	solated. 25V 10mA	
Excitation Timing Output (MONI)	This MONI output is a sequence. Full Step : one pulse out	octivated when the drive	r is at origin (step zero) Half Step : one pulse output	

IMS51cat-122004-V1.0 Page 1 of 10

Dielectric Strength	No abnormality detected after the application of the below voltage among each terminal for one minute in normal temperature and humidity: Power input terminal – PE terminal 2KV (for 100V input type) 3KV (for 200V input type) Power input terminal – Signal I/O terminal 2KV (f00V type) 3KV (200V type)			
Insulation Resistance	100M ohms or higher with DC500V applied in normal temperature and humidity. • Between Voltage- input terminal Case • Between Voltage- input terminal and Signal terminal			
Applicable Standard	EN60950			
Operating Environment	Temperature: 0 ~ +40°C No freezing Humidity: less than 80% No condensation			
Storage Environment	Temperature : -10 ~ +60°C No freezing Humidity : less than 80% No condensation			
Operating Height	Less than 1,000m from sea level			
Atmosphere	In the room without corrosive gas, inflammable gas or dust, without splashing water or oil.			
Weight	1 Kg			

2. Applicable Motor Range

	Motor Size		Max. Holding	Rotor Inertia	Basic Step	Phase Current	Motor
Type	(mm)	Motor Model	Torque (kgcm)	(gcm²)	Angle***	(Amps)	Weight (kg)
HI-TORQUE		PCE 5641 AC (BC)	4.2	175	0.72°	1.4	0.6
	60	PCE 5661 AC (BC)	8.3	280	0.72°	1.4	0.8
		PCE 5691 AC (BC)	16.6	560	0.72°	1.4	1.3
		PCE 5961 AC (BC)	21	1400	0.72°	1.4	1.7
	85	PCE 5991 AC (BC)	41	2700	0.72°	1.4	2.8
		PCE 59131 AC (BC)	63	4000	0.72°	1.4	3.8
HI-TORQUE		PCE 5641 ACM	4.2	320	0.72°	1.4	0.9
TII-TORQUE	60	PCE 5661 ACM	8.3	425	0.72°	1.4	1.1
	00	PCE 5691 ACM	16.6	705	0.72°	1.4	1.6
*Brake Type		PCE 5961 ACM	21	2200	0.72°	1.4	2.4
Brake Type	0.5						
	85	PCE 5991 ACM	41	3500	0.72°	1.4	3.5
		PCE 59131 ACM	63	4800	0.72°	1.4	4.5
HI-TORQUE	60	PCE 5692 AC (BC)	16.6	560	0.72°	2.8	1.3
HI-SPEED		PCE 5962 AC (BC)	21	1400	0.72°	2.8	1.7
	85	PCE 5992 AC (BC)	41	2700	0.72°	2.8	2.8
		PCE 59132 AC (BC)	63	4000	0.72°	2.8	3.8
		` '	1	Į.			Į.
HI-TORQUE	60	PCE 5692 ACM	16.6	705	0.72°	2.8	1.6
HI-SPEED		PCE 5962 ACM	21	2200	0.72°	2.8	2.4
	85	PCE 5992 ACM	41	3500	0.72°	2.8	3.5
*Brake Type	00	PCE 59132 ACM	63	4800	0.72°	2.8	4.5

Note: Motor model ending with A or AC - single shaft Motor model ending with B or BC - double shaft

*** refer to resolution selection table for step angle setting

Motor Electrical Specifications

Dielectric Strength	No abnormality detected after the application of 0.5KV at 50 Hz between motor windings and frame for duration of one minute		
Insulation Resistance	100 Mohms or better with 500V potential applied between motor windings and frame at normal ambient temperature and humidity		
Insulation Class	Class B	Operating Environment Temperature	0°C ~ + 50°C

Motor Mechanical Specifications

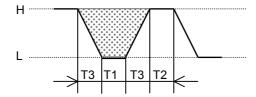
Shaft Radial Play	0.025 mm (max) at load 0.5 Kg
Shaft Axial Play	0.075mm (max) at load 1 Kg
Step Angle Accuracy	± 3 min

IMS51cat-122004-V1.0 Page 2 of 10

Signal Input Waveform



5-1. Input Signal Waveform



 $T1 \ge 6\mu sec$ $T2 \ge 10\mu sec$ $T3 \le 2\mu sec$

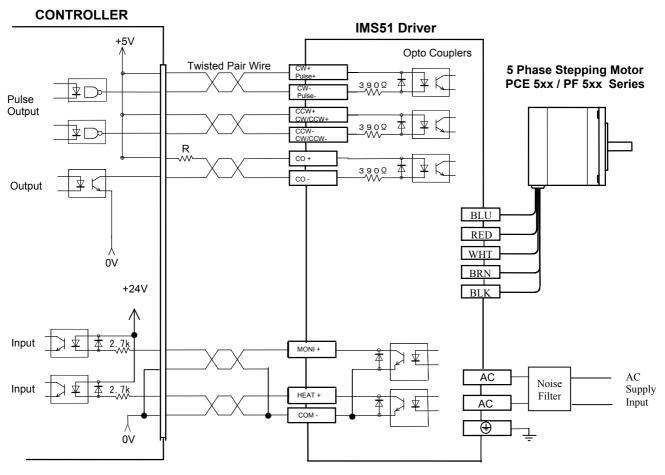
Shaded area shows "ON" of photo coupler at input circuit.
The rising edge activates the motor.

Automatic Current Down

This driver is equipped with the auto-current down function where the motor current is reduced at stand still status. This reduces the motor heat build up when not running.

The factory setting is at 50% of the motor running current, user can adjust this setting via the CC.ADJ trimpot. The function is activated 200 msec after the motor stops. i.e. pulse input changes from H to L.. This function can be deactivated by the A.CD DIP Switch setting.

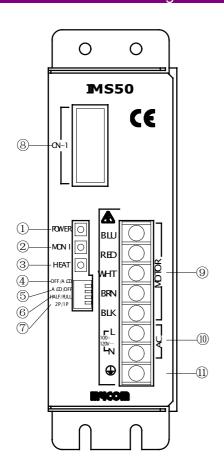
7. Connection Diagram



^{*(}If controller outputs are DC24V, a resistor of value R = 1.2kΩ 1/2W is to be connected in series to the signals. Not necessary if the outputs are DC5V.)

IMS51cat-122004-V1.0 Page 7 of 10





Power Indicator LED

MONI LED

This MONI output is activated when the driver is at origin (step zero) in the excitation sequence.

FULL Step: one pulse output at every 10th step HALF Step: one pulse output at every 20th step

(3) Overheat Indicator LED

This Overheat indicator LED lights up when the temperature sensor in the driver detected over 70°C.

(4) Auto Current Down Function (A.CD)

This switch enables/disables the function of Auto Current Down Feature of the driver. When enabled, the motor driving current is reduced to 50% (default) (or setting as in CC.ADJ trimpot) of the motor running current. This current reduction feature helps to reduce the temperature of the motor when it is not in operation. The current down feature is activated 200 msec after the last pulse input received (determined by the non-conducting state of Clock input). It is recommended to ENABLE this function.

Disabled		Enabled		
OFF/A .CD	9 -	OFF/A .CD	9-□	
A CO,OFF	~~	A CO,OFF	_ ∾⊏	
HALF/FULL	ω	HALF/FULL	ω□	
2P/1P	4	2P/1P	4	

(5) Auto Current OFF Function (A.CO)

This switch enables/disables the function of Auto Current Off Feature of the driver. When enabled, the motor driving current is switched OFF when the internal temperature sensor of the driver detected a temperature exceeding 70 deg Celsius.

Enabled		Disabled		
OFF/A .CD	<u>5-</u> ∟	OFF/A .CD	5- □	
A CO/OFF	Ī	A .CO,OFF	_ YI	
HALF/FULL	υL	HALF/FULL	υþ	
2P/1P	4	2P/1P	4	

(6) HALF/FULL Step Selection (HALF/FULL)

This switch selects the step angle resolution of the motor angle as follows :-

HALF: 1000 ppr (0.36 deg/step) FULL: 500 ppr (0.72 deg / step)

HALF	Step	FULL Step		
OFF/A .CD	5 -L	OFF/A .CD	9 +	
A £O,OFF	⁻ ~	A .CO,OFF	²	
HALF/FULL	υ	HALF/FULL	ω	
2P/1P	4	2P/1P	4	

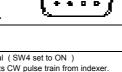
(7) Input Pulse Type Selection Switch (2P/1P)

This switch sets the Type of Input Pulse for the driver. 2P: Bi-Clock (CW, CCW clock input) - Default setting 1P: 1 Clock (Gate / Direction input)

Bi-Clock Type Gate/Direction Type

OFF/A .CD	9-∟	OFF/A .CD	₹-
A £O,OFF	2	A £O,OFF	7
HALF/FULL	ω	HALF/FULL	ω
2P/1P	4	2P/1P	4

(8) Signal I/O connector (CN-1) CN Driver Signal connection ::-



Pin#	Driver S	Signal	Description		Pin#	Driver Signal	Description	
1	CW+	- (Dl s.)	CW pulse input terminal (SW4 set to ON) This opto-isolated inputs CW pulse train from indexer.		5	CO+	Motor current shutoff input terminal (CO) The driver's output current can be turned off by this input.	
2	CW-	(Pulse)	Step / Pulse input terminal (SW4 set to OFF) This opto-isolated inputs motor step pulses from indexer.		6	CO-	The motor will not run while this input is ON.	
3	CCW+	-(DIR)	CCW pulse input terminal (SW4 set to ON) This opto-isolated inputs CCW pulse train from an indexer. Direction input terminal (SW4 set to OFF)	Il (SW4 set to ON) CCW pulse train from an SW4 set to OFF) CW/CCW direction input.	7	MONI+	Excitation timing output terminal. This is an open collector output which turns on once per : every 10 th pulses received (FULL step - SW3 OFF), every 20 th pulses received (HALF step - SW3 ON).	
4	CCW-	- (2 1)	This opto-isolated inputs CW/CCW direction input.			8	HEAT+	Overheat Output terminal
9	COM-		This is the common for MONI and HEAT output.		8	I ILAI T	This is an open collector output which turns on when the driver temperature exceeds 70°C.	

(9) **Motor Lead terminals** (Motor power outputs)

Connect motor leads to these terminals according to the color code.

(11) Frame Ground (PE)

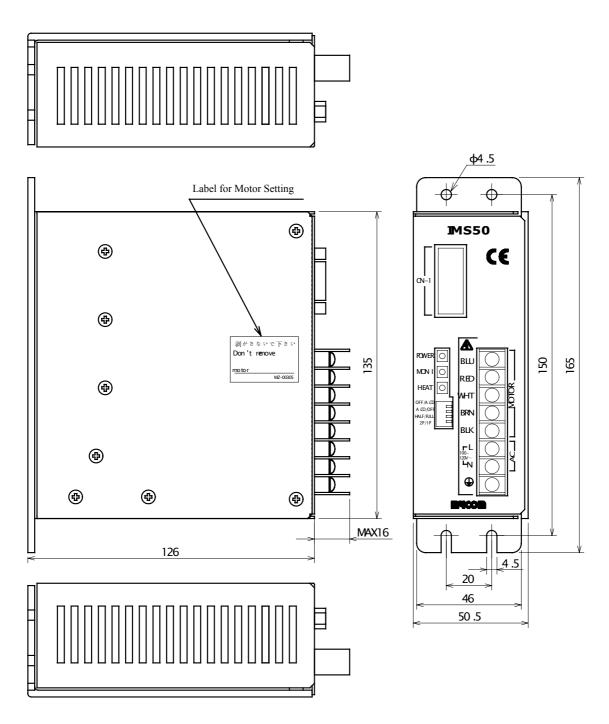
Connect to system ground point. Use AWG18 (0.75mm²) or larger leads for connection.

(10) AC Power Input Terminal

Connect Single phase supply to these terminals as follows: Model IMS51-110 / IMS51-210 : 100V~120Vac 50/60Hz Model IMS51-120 / IMS51-220 : 200V~220Vac 50/60Hz (Use AWG18 (0.75mm²) or larger leads for connection.)

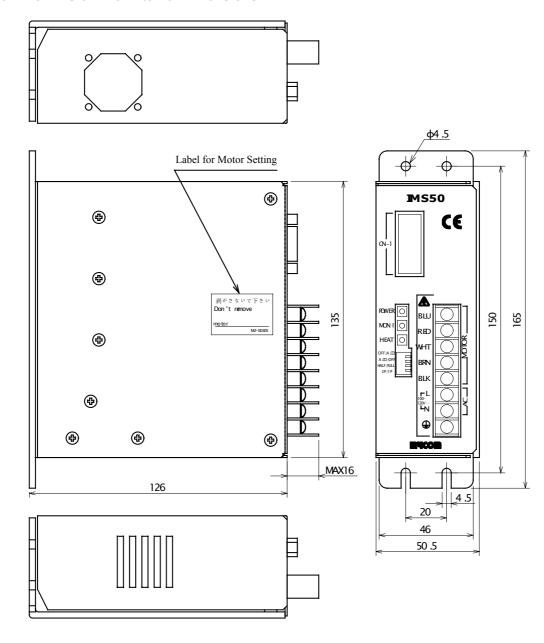


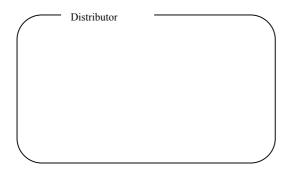
IMS 51-110 / IMS 51-120 External Dimensions



IMS51cat-122004-V1.0 Page 9 of 10

IMS 51-210 / IMS 51-220 External Dimensions





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IMS51cat-122004-V1.0

^{**} MYCOM reserves the right to revise the specifications, dimensions etc of the above product without obligation to notify any person of such revision or changes.